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PRESS RELEASE

Day, Month, 2026.

Place

EVENTS Project Successfully Concludes: Strengthening Trust in Automated Mobility

Innovative technologies tested in real-world conditions pave the way for safer automated driving in Europe

After 3.5 years of intensive research, development, and large-scale experimentation, the European research project [EVENTS](#) has successfully concluded, delivering significant results that contribute to safer and more trustworthy automated driving systems.

The [EVENTS](#) project brought together 12 partners from 8 EU countries and the United Kingdom, including leading universities, research institutes, and industry stakeholders across Europe such as the [Institute of Communication & Computer Systems \(ICCS\)](#), [Centro Ricerche Fiat SCPA \(CRF\) – Stellantis](#), [the University of ULM](#), [Seability Ltd](#), [Fundacion Technalia Research & Innovation \(TECN\)](#), [the Delft University of Technology \(TUD\)](#), [HITACHI France](#), & [UK](#), [APTIV Deutschland & Poland](#), [APTIV France](#), [the University of Warwick \(WMG\)](#) and [Perciv AI](#).

Building on its extensive expertise in intelligent transport systems and automated mobility, the project consortium, successfully developed and validated an advanced perception and decision-making framework for automated vehicles. The project focused on testing how automated systems respond to complex and uncertain driving conditions, helping vehicles detect, interpret, and safely react to challenging real-world situations.

Throughout the project, a wide range of real-life scenarios that automated vehicles may encounter on European roads were investigated. These included unstructured road environments such as missing lane markings, the presence of vulnerable road users including cyclists and pedestrians, adverse weather conditions, limited visibility situations, as well as failures in sensors or vehicle communication systems.

To address these challenges, the [EVENTS](#) project conducted extensive testing activities that included:

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- Integration of advanced sensing technologies, including cameras, radar, and LiDAR, combined with intelligent perception algorithms.
- Experiments involving interactions with vulnerable road users in complex urban environments.
- Performance evaluation of automated systems in low-visibility conditions.
- Scenarios involving uncertainty, where the vehicle must assess the reliability of its sensor data.
- Activation of safe manoeuvring strategies when the system detects reduced confidence in the available data.

According to **PARNTER's NAME, ROLE, INSTITUTION: "QUOTE"**.


The key outcomes of the project were presented during the [EVENTS](#) Final Event, which took place in Delft, the Netherlands, in late February 2026, bringing together researchers, industry representatives, and stakeholders from across the automated mobility ecosystem to delve into the project's results, participating also in two ay vehicle demonstrations.

With its successful completion, the [EVENTS](#) project contributes valuable technological advancements and experimental evidence that support the safe, reliable, and trustworthy deployment of automated mobility solutions in Europe.


More information about the project and its results is available at: <https://www.events-project.eu/>

For more information: please contact [\[add partners details here\]](#)

Editor Notes

Duration:	01 September 2022 – 28 February 2026 (42 months)
Contract Number:	101069614
Estimated Project Cost:	€ 6,920,598.00
Requested EU Contribution:	€ 5,534,448.00
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	<i>European Commission. Neither the European Union nor the granting authority can be held responsible for them.</i>
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