



**Reliable in-Vehicle pErception and decisioN-making in
complex environmenTal conditionS**

Grant Agreement Number: 101069614

EVENTS Final Event

AGENDA

Date:	25 February 2026
Time	10:30 – 16:00 CET
Venue:	Delft, The Netherlands & Online Venue: Mechanical Engineering Faculty, TU Delft Mekelweg 2, 2628 CD (front building, by public transport) Leeghwaterstraat 5, 2628 CA (rear building, by car) Meeting room "Lagerhuysch"
Organisers:	TUD, ICCS, SEAB



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CONSORTIUM

1	INSTITUTE OF COMMUNICATION AND COMPUTER SYSTEMS (ICCS)
2	CENTRO RICERCHE FIAT SCPA (CRF)
3	UNIVERSITAET ULM (UULM)
4	NAYTILIAKES METAFORIKES KAI EPIKOINONIAKES EPIXEIRISEIS SEABILITY EPE (SEAB)
5	FUNDACION TECNALIA RESEARCH & INNOVATION (TECN)
6	TECHNISCHE UNIVERSITEIT DELFT (TUD)
7	HITACHI EUROPE SAS (HIT-FR)
8	APTIV SERVICES DEUTSCHLAND GMBH (APTIV)
9	PERCIV B.V. (PERCIV)
10	HITACHI EUROPE LIMITED (HIT-UK)
11	THE UNIVERSITY OF WARWICK (WMG)

Time slot	Presentation title & Speaker
10:30-10:50	Registration & Coffee
10:50-11:00	EU Intervention <i>Marzena (Skubij) Jougonoux, Policy Officer, European Commission</i>
11:00-11:10	Welcome note by EVENTS Coordinator <i>Dr. Angelos Amditis, Research & Development Director ICCS/NTUA</i>
11:10-11:20	Welcome note by the Local Organizer <i>Prof. Dariu Gavrilă, Professor, Delft University of Technology</i>
11:20-11:40	Sharing the Road: Autonomous Vehicles in Urban Environment <i>Prof. Dariu Gavrilă, Professor, Delft University of Technology</i> Automated Collision Avoidance on the Slippery Roads <i>Prof. Barys Shyrokau, Associate Professor, Delft University of Technology</i> Driving in slow speed roads with bad weather: How well Autonomous Vehicles understand their surroundings <i>Dr. Andras Palffy, Co-Founder, Perciv AI</i>
11:40-12:00	How Autonomous Vehicles Re-Form Platoons After a Roundabout <i>Asier Arizala, Investigation Engineer, Tecnalia Research Centre</i> <i>Konstantinos Lazaridis, Software Developer, I-SENSE Group of ICCS</i>
12:00-12:20	Self-Assessment in Autonomous Vehicle Perception with Complementary Vehicle-to-Everything Communication <i>Florian Hillitzer, Research Assistant, Ulm University</i>
12:20-12:30	Coffee Break
12:30-12:50	Deciding the next move: Helping Autonomous Vehicles navigate in complex road conditions <i>Asier Arizala, Investigation Engineer, Tecnalia Research Centre</i> Entering Highway Traffic: How Autonomous Vehicles Perceive Safe Merges <i>Massimiliano Lenardi, Corp. R&D Manager FR&DE, Hitachi European R&D</i>
12:50-13:05	Seeing the Hard-to-See: Detecting Small Objects at Long Distances in Bad Weather <i>Dr. Kirsty Aquilina - Data Scientist, Aptiv DE</i> <i>Yannis Mraïhi - Vehicle System Integration Engineer, Aptiv FR</i>
13:05-13:20	Driving Smarter in Tough Conditions: Resilient Onboard Perception and Anticipating other vehicles' behaviour <i>Dr. Kostas Koufos, Lecturer, The Queen's University Belfast, WMG</i>

	<i>Dr. Bill Roungas, EVENTS Project Manager, I-SENSE Group of ICCS</i>
13:20-14:10	Lunch Break
14:10-15:00	Vehicle Demo: Interaction of Automated Vehicle with Vulnerable Road Users <i>Delft University of Technology & Perciv AI</i>
15:00-15:35	Vehicle Demo: Radar-First Perception for on-road and off-road autonomy <i>Perciv AI</i>
15:45-15:55	Q&A
15:55-16:00	Wrap Up <i>Dr. Bill Roungas, EVENTS Project Manager, I-SENSE Group of ICCS</i>
End of Day	