



**Reliable in-Vehicle pErception and decisioN-making in  
complex environmenTal conditionS**

**Grant Agreement Number: 101069614**

**EVENTS Final Event**

**AGENDA**

<b>Date:</b>	25 February 2026
<b>Time</b>	10:30 – 16:00 CET
<b>Venue:</b>	Delft, The Netherlands & Online Venue: Mechanical Engineering Faculty, TU Delft Mekelweg 2, 2628 CD (front building, by public transport) Leeghwaterstraat 5, 2628 CA (rear building, by car) Meeting room "Lagerhuysch"
<b>Organisers:</b>	TUD, ICCS, SEAB



This project has received funding under grant agreement No 101069614. It is funded by the European Union. Views and opinions expressed are however those of the author(s) only and do not necessarily reflect those of the European Union or European Commission. Neither the European Union nor the granting authority can be held responsible for them.

## CONSORTIUM

1	INSTITUTE OF COMMUNICATION AND COMPUTER SYSTEMS (ICCS)
2	CENTRO RICERCHE FIAT SCPA (CRF)
3	UNIVERSITAET ULM (UULM)
4	NAYTILIAKES METAFORIKES KAI EPIKOINONIAKES EPIXEIRISEIS SEABILITY EPE (SEAB)
5	FUNDACION TECNALIA RESEARCH & INNOVATION (TECN)
6	TECHNISCHE UNIVERSITEIT DELFT (TUD)
7	HITACHI EUROPE SAS (HIT-FR)
8	APTIV SERVICES DEUTSCHLAND GMBH (APTIV)
9	PERCIV B.V. (PERCIV)
10	HITACHI EUROPE LIMITED (HIT-UK)
11	THE UNIVERSITY OF WARWICK (WMG)

Time slot	Presentation title & Speaker
10:30-10:50	Registration & Coffee
10:50-11:00	EU Intervention <i>Marzena (Skubij) Jougonoux, Policy Officer, European Commission</i>
11:00-11:10	Welcome note by EVENTS Coordinator <i>Dr. Angelos Amditis, Research &amp; Development Director   ICCS/NTUA</i>
11:10-11:20	Welcome note by the Local Organizer <i>Prof. Dariu Gavrilă, Professor, Delft University of Technology</i>
11:20-11:40	Sharing the Road: Autonomous Vehicles in Urban Environment <i>Prof. Dariu Gavrilă, Professor, Delft University of Technology</i> Driving in slow speed roads with bad weather: How well Autonomous Vehicles understand their surroundings <i>Dr. Andras Palffy, Co-Founder, Perciv AI</i> Automated Collision Avoidance on the Slippery Roads <i>Prof. Barys Shyrokau, Associate Professor, Delft University of Technology</i>
11:40-12:00	How Autonomous Vehicles Re-Form Platoons After a Roundabout <i>Asier Arizala, Investigation Engineer, Tecnalia Research Centre</i> <i>Konstantinos Lazaridis, Software Developer, I-SENSE Group of ICCS</i>
12:00-12:20	Self-Assessment in Autonomous Vehicle Perception with Complementary Vehicle-to-Everything Communication <i>Florian Hillitzer, Research Assistant, Ulm University</i>
12:20-12:30	Coffee Break
12:30-12:50	Deciding the next move: Helping Autonomous Vehicles navigate in complex road conditions <i>Asier Arizala, Investigation Engineer, Tecnalia Research Centre</i> Entering Highway Traffic: How Autonomous Vehicles Perceive Safe Merges <i>Massimiliano Lenardi, Corp. R&amp;D Manager FR&amp;DE, Hitachi European R&amp;D</i>
12:50-13:05	Seeing the Hard-to-See: Detecting Small Objects at Long Distances in Bad Weather <i>Dr. Kirsty Aquilina - Data Scientist, Aptiv DE</i> <i>Yannis Mraïhi - Vehicle System Integration Engineer, Aptiv FR</i>
13:05-13:20	Driving Smarter in Tough Conditions: Resilient Onboard Perception and Anticipating other vehicles' behaviour <i>Dr. Kostas Koufos, Lecturer, The Queen's University Belfast, WMG</i>

	<i>Dr. Bill Roungas, EVENTS Project Manager, I-SENSE Group of ICCS</i>
13:20-14:10	Lunch Break
14:10-14:50	Vehicle Demo: Interaction of Automated Vehicle with Vulnerable Road Users <i>Delft University of Technology</i>
14:50-15:25	Vehicle Demo: Radar-First Perception for on-road and off-road autonomy <i>Perciv AI</i>
15:25-15:30	Wrap Up <i>Dr. Bill Roungas, EVENTS Project Manager, I-SENSE Group of ICCS</i>
<b>End of Day</b>	