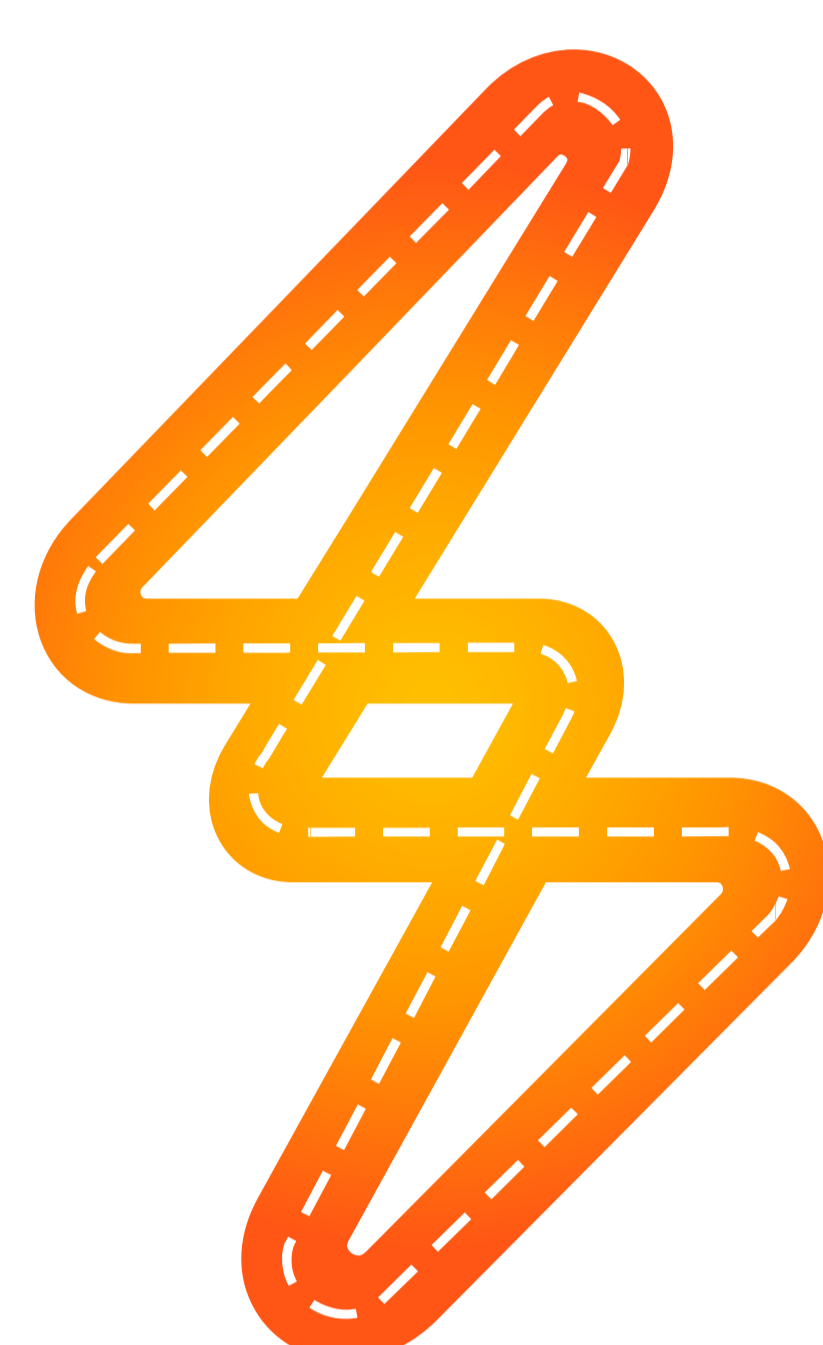


reliable
in-Vehicle
pErception and
decisioN-making
in complex
environmenTal
conditionS



EVENTS

Robust perception and decision-making for automated driving

The vision of EVENTS project is to create a robust and resilient perception and decision-making system for Connected and Automated Vehicles (CAVs) to manage various types of “events” on the horizon.

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STELLANTIS



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